

# PE LVRT and P(f) Response

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POWER-ELECTRONICS.COM 2024-01-01

# LVRT Response

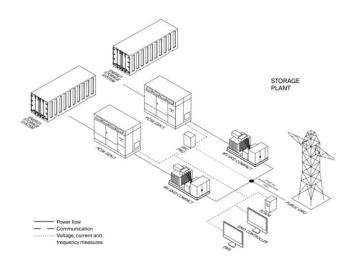
- Response based on P&Q at event T=0 i.e. Is<sub>prev</sub> + KDV
- Q Response based on V Threshold and K Value
- During LVRT, PPC setpoints are ignored
- Exit Response Based on LVRT Recovery Ramp Rates
- Inverter may trip if Voltage and Frequency protection trip settings are exceeded.

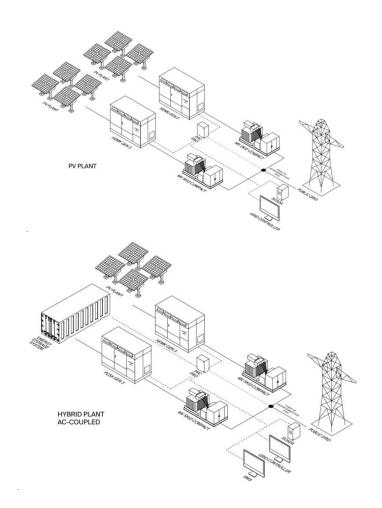
### Powerful, accurate and flexible

#### Flexible PLC Technology

Real-time control and monitoring for advanced utility-scale applications.

- Solar
- Standalone storage applications [1]
- Hybrid plants- AC coupled [1]
- Self-consumption
- Zero grid injection systems





- . ERCOT is seeing issues with IBR plants measuring and responding to frequency during VRT events, frequency spikes are being erroneously measured and then PPC responds to those once the event is over, which means it either sends the plant output in the wrong direction or doesn't let the plant's MW recover because it "thinks" there 's an over frequency event.
- ERCOT is looking for OEMs presentations about how they do things today in terms of hand over between VRT mode (which is at inverter level) and PFR response (which is usually at PPC level) as well as how frequency measured & filtered for PFR response. Also, of interest is to understand how an inverter enters and exists VRT mode, i.e. what is driving it, assuming it's voltage, is it instantaneous value, if not what is the measurement window, any time delays there

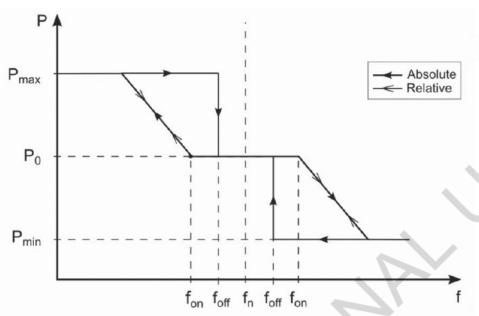
# Inverter parameters and Algorithms

- Voltage and Frequency Protection settings
- Inverter power output P\_limit (solar) and P\_set (ESS)
- P and Q Ramp Rate limits
- LVRT and OVRT Algorithms
- Frequency Droop Curves

### Inverter Frequency Droop Curve

#### Subgroup G4.7: P(f) Curve

This subgroup allows the configuration of the P(f) algorithm. The following graph represents the algorithm curve.



# FFR – Central Controller response

#### 3.1 Central Controller Option

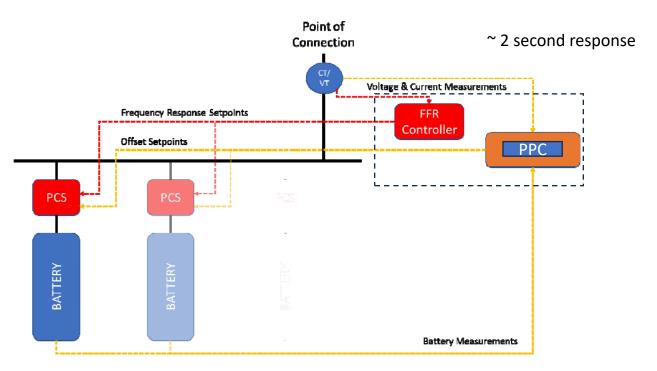


Figure 2 - Central FFR controller

# FFR – Central Controller response

#### 3.1 Central Controller Option

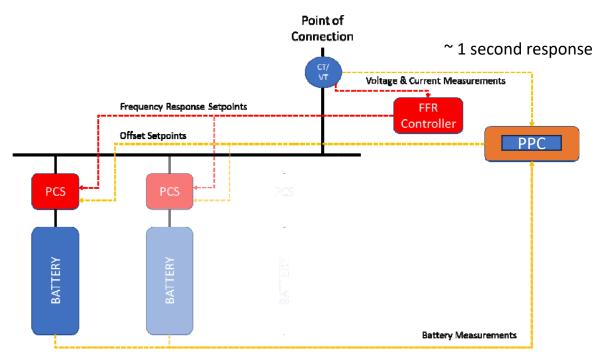


Figure 2 - Central FFR controller

# FFR – Independent inverter response

#### 3.2 PCS Controller Option

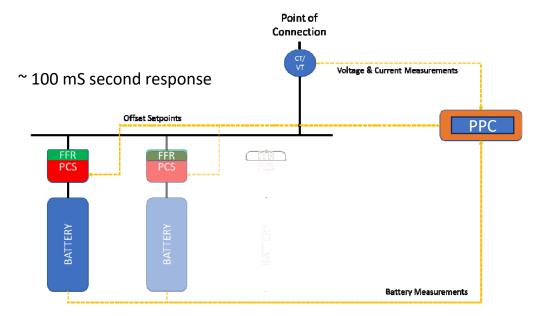
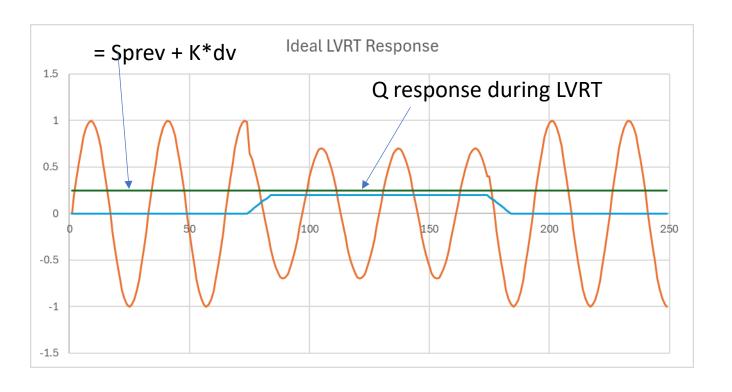
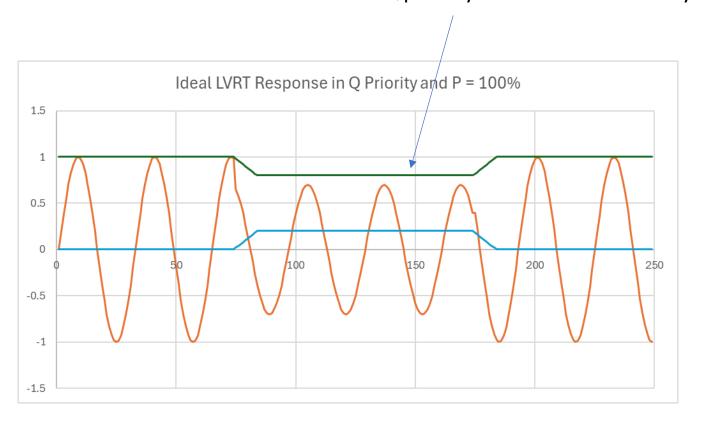


Figure 2 -FFR control devolved to PCSs

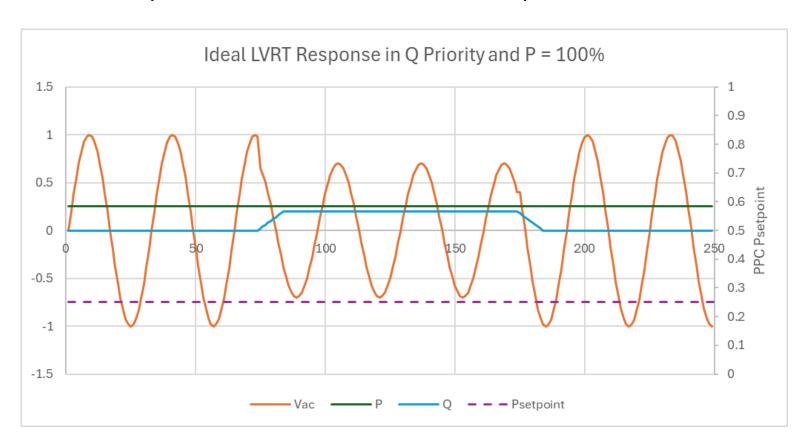
### Ideal LVRT Response



# LVRT Response with $P = P_{\text{In Q priority P is reduced to satisfy Q}}$

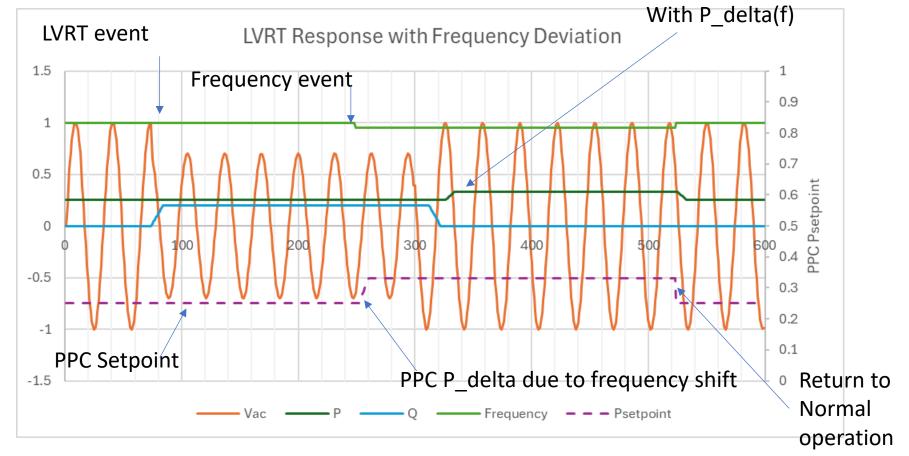


# LVRT Response and PPC Pset response



### LVRT Response with Frequency Deviation

Pout post LVRT response



# Exiting LVRT Mode

- Configurable Parameters
  - Maximum LVRT Duration
  - Delay time
  - Hysteresis
  - P & Q Recovery setpoints
  - Recovery ramps for P & Q

# Appendix

# **Voltage Protections**

#### LVRT protections

Screen	Range	Recommended Value	Function	Set on run
G5.1.1.1-Enable	Slow: Y / N Fast: Y / N Fast 2: Y / N Very fast: Y / N Very fast 2: Y / N	YYYYN	There are five low voltage protection levels: - Slow protection - Fast protection - Fast 2 protection - Very fast protection - Very fast 2 protection To enable each protection, set the corresponding bit to Yes and adjust the voltage values and delay as desired (parameters G5.1.1.2 to G5.1.1.11).	Yes
G5.1.1.2-Slow protection	0.0 to 100.0 %	85.0%	Protection levels can be set from 0.0% up	Yes
G5.1.1.3-Delay slow protection	0.0 to 6550.0 s	10.0	to 100.0%. 100.0% corresponds with the rated voltage.	Yes
G5.1.1.4-Fast protection	0.0 to 100.0%	65.0%	The slow protection delay can be set from	Yes
G5.1.1.5-Delay fast protection	0.0 to 655.00 s	5.00	0.0 s up to 6550.0 s. Fast protections delay can be set from 0.00 s up to 655.00	Yes
G5.1.1.6-Fast 2 protection	0.0 to 100.0 %	45.0%	s.	Yes
G5.1.1.7-Delay fast 2 protection	0.00 to 655.00 s	2.00	Very fast protections delay range varies between 0.000 s and 65.500 s.	Yes
G5.1.1.8-Very fast protection	0.0 to 100.0%	20.0%	It is possible to enable/disable each	Yes
G5.1.1.9-Delay very fast prot	0.000 to 65.500 s	1.00	protection level individually in G5.1.1.1.  Default values, on the other hand, depend on the selected normative.	Yes
G5.1.1.10-Very fast 2 protection	0.0 to 100.0%	Disabled	on the selected normalize.	Yes
G5.1.1.11-Delay very fast 2 prot	0.000 to 65.500 s	Disabled		Yes

#### OVRT protections

Screen	Range	Recommended Value	Function	Set on run
G5.1.2.1-Enable	Slow: Y / N Fast: Y / N Fast 2: Y / N Very fast: Y / N Very fast 2: Y / N	YYNYN	There are five low voltage protection levels: - Slow protection - Fast protection - Fast 2 protection - Very fast protection - Very fast 2 protection - Very fast 2 protection To enable each protection, set the corresponding bit to Yes and adjust the voltage values and delay as desired (parameters G5.1.2.1 to G5.1.2.11).	Yes
G5.1.2.2-Slow protection	100.0 to 150.0 %	115.0%	Protection levels can be set from 0.0% up	Yes
G5.1.2.3-Delay slow prot	0.0 to 6550.0 s	2.0		Yes
G5.1.2.4-Fast protection	100.0 to 150.0 %	125.0%	to 150.0%. 100.0% corresponds with the	Yes
G5.1.2.5-Delay fast protection	0.00 to 655.00 s	0.10	rated voltage.	Yes
G5.1.2.6-Fast 2 protection	100.0 to 150.0 %	Disabled	The slow protection delay can be set from 0.0 s up to 6550.0 s. Fast protections	Yes
G5.1.2.7-Delay fast 2 protection	0.00 to 655.00 s	Disabled	delay can be set from 0.00 s up to 655.00 s.	Yes
G5.1.2.8-Very fast protection	100.0 to 150.0%	140.0%	Very fast protections delay range varies between 0.000 s and 65,500 s.	Yes
G5.1.2.9-Delay very fast prot	0.000 to 65,500 s	0.003	It is possible to enable/disable each	Yes
G5.1.2.10-Very fast 2 protection	100.0 to 150.0%	Disabled	protection level individually in G5.1.2.1.  Default values, on the other hand, depend on the selected normative.	Yes
G5.1.2.11-Delay very fast 2 prot	0.000 to 65.500 s	Disabled		Yes

## Frequency Protections

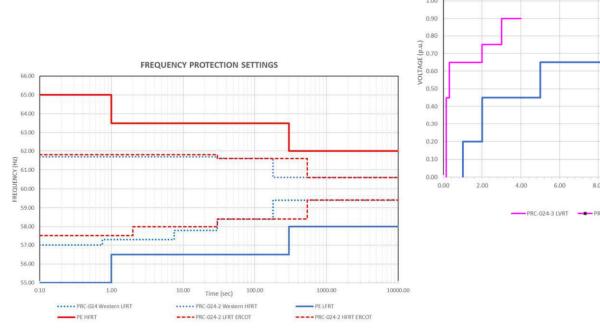
#### LFRT protections

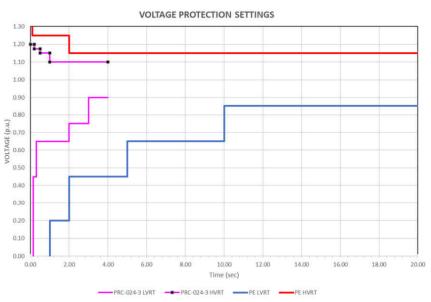
Screen	Range	Recommended Value	Function	Set on run
G5.1.3.1-Enable	Slow: Y / N Slow 2: Y / N Fast: Y / N Very fast: Y / N Very fast 2: Y / N	YYYNN	There are five low frequency protection levels: - Slow protection - Slow 2 protection - Fast protection	Yes
G5.1.3.2-Slow protection	45.0 to 60.0 Hz	58.0	- Very fast protection	Yes
G5.1.3.3-Delay slow protection	0.0 to 6550.0 s	300.0	- Very fast 2 protection To enable each protection, set the corresponding bit to Yes.  Protection levels can be set from 45.0 Hz up to 60.0 Hz.	Yes
G5.1.3.4-Slow 2 protection	45.0 to 60.0 Hz	56.5		Yes
G5.1.3.5-Delay slow 2 protection	0. to 6550.0 s	1.0		Yes
G5.1.3.6-Fast protection	45.0 to 60.0 Hz	55.0	The slow protection delay can be set from	Yes
G5.1.3.7-Delay fast protection	0.00 to 655.00 s	0.10	0.0 s up to 6550.0 s. Fast protections delay can be set from 0.00 s up to 655.00	Yes
G5.1.3.8-Very fast protection	45.0 to 60.0 Hz	disabled	s.  Very fast protections delay range varies	Yes
G5.1.3.9-Delay very fast prot	0.000 to 65.500 s	disabled	between 0.000 s and 65.500 s.	Yes
G5.1.3.10-Very fast 2 protection	45.0 to 60.0 Hz	disabled	It is possible to enable/disable each protection level individually in G5.1.3.1.	Yes
G5.1.3.11-Delay very fast 2 prot	0.000 to 65,500 s	disabled	Default values, on the other hand, depend on the selected normative.	Yes

#### OFRT protections

Screen	Range	Recommended value	Function	Set on run
G5.1.4.1-Enable	Slow: Y / N Slow 2: Y / N Fast: Y / N Very fast: Y / N Very fast 2: Y / N	YYYNN	There are five low frequency protection levels: - Slow protection - Slow 2 protection - Fast protection	Yes
G5.1.4.2-Slow protection	50.0 to 65.0 Hz	62.0	- Very fast protection	Yes
G5.1.4.3-Delay slow protection	0.0 to 6550.0 s	300.0	- Very fast 2 protection To enable each protection, set the corresponding bit to Yes.  Protection levels can be set from 50.0 Hz up to 65.0 Hz.	Yes
G5.1.4.4-Slow protection	50.0 to 65.0 Hz	63.5		Yes
G5.1.4.5-Delay slow protection	0.0 to 6550.0 s	1.0		Yes
G5.1.4.6-Fast protection	50.0 to 65.0 Hz	65.0		Yes
G5.1.4.7-Delay fast protection	0.00 to 655.00 s	0.10	Slow protection delays can be set from 0.0 s up to 6550.0 s. The fast protection delay can be set from 0.00 s up to 655.00 s.	Yes
G5.1.4.8-Very fast protection	50.0 to 65.0 Hz	disabled		Yes
G5.1.4.9-Delay very fast prot	0.000 to 65.500 s	disabled	Very fast protections delay range varies between 0.000 and 65.500 s.	Yes
G5.1.4.10-Very fast 2 protection	50.0 to 65.0 Hz	disabled	It is possible to enable/disable each	Yes
G5.1.4.11-Delay very fast 2 prot	0.000 to 65.500 s	disabled	protection level individually in G5.1.4.1. Default values, on the other hand, depend on the selected normative.	Yes

### PE Voltage and Frequency Protections





### LVRT Algorithm Options

Screen	Range	Recommended value	Function		Set on run	l
				This parameter allows enabling the algorithm to define the behavior of the inverter during a voltage dip event.		
			OPTION	DESCRIPTION		l
			Disabled	LVRT algorithm is disabled.		l
G4.3.1.1-Enable	Disabled Mode 1	Disabled Mode 1 Mode 2 Mode 3	Mode 1	Enable low voltage ride-through. The reference voltage corresponds with the direct sequence voltage.		
	Mode 2 Mode 1		Mode 2	Enable low voltage ride-through. The reference voltage corresponds with the lowest value of phase-to-phase voltages.		
			Mode 3	Enable the algorithm. The LVRT algorithm considers the estimated voltage in the POI to access or not to LVRT.		
		l	his parameter is set to Disabled, the rest of s within this group will not be shown.			
G4.3.1.2- Threshold	0.0 to 95.0%	85.0%	Sets the threshold for the LVRT algorithm. If the voltage goes under this value, the algorithm will be executed.		Yes	
G4.3.1.3- Moment. cessation	0.0 to 100.0% Off = 1001	Off	It configures a nominal voltage threshold below which the inverter does not inject power to the grid anymore (P=0; Q=0)		Yes	

LVRT Mode Select (Mode 1 is most popular)

LVRT threshold

Momentary cessation typically Disabled

### LVRT Configuration Continued

Screen	Range	Recommended value	Function			
		value			run	
			Selects the behavior in case of a dip event:			
			OPTION	DESCRIPTION		
			kdV	Response is proportional to voltage variation.		
	kdV		lq prev + kdVdir	Response is proportional to the direct sequence voltage variation + previous reactive power.		
G4 3 1 4-	lq prev + kdVdir Is prev +		ls prev + kdVdir	Response is proportional to the direct sequence voltage variation + previous apparent power.		
Configuration	kdVdir Proportiona I Advanced	Is prev + kdV	Proportional	The response tries to maintain the pre-event direct sequence active and reactive power and adds reactive current in direct and reverse sequence proportional to the voltage variation, limiting both currents equally (proportional). Prioritizes the injection of Q over P.		
			Advanced	Allows configuring a customized behavior.  Once this option is selected, parameters [Injection mode Id] and [-Injection mode Iq] will be shown.		
			Allow selecting	the P control mode:		
G4.3.1.5- P	Current	Current	OPTION	DESCRIPTION	Yes	
Control mode	Power		Current	Control by current,		
			Power	Control by power.		
			Allow selecting	the Q control mode:		
G4.3.1.6-Q	Current	Current	OPTION	DESCRIPTION	Yes	
Control mode	Power	Guiteik	Current	Control by current.	""	
			Power	Control by power.		
G4.3.1.7-P/Q priorit y	P Q	Q	This parameter allows deciding which magnitude P or Q will take priority to keep S constant at a maximum value. P selects active power priority and Q selects reactive power priority.		Yes	
G4.3.2.7-K dir	0.0 to 10.0	2.0	Adjusts the K multiplying factor for direct sequence during operation in LVRT. $\ensuremath{\gamma}$			

# Define starting P&Q starting point For LVRT event

#### LVRT Exit Parameters

SCREEN	RANGE	DESCRIPTION	SET ON RUN
G4.3.3.1-Threshold Delay = Infinite	0.005 to 60.000 s Infinite = 60.001;	Sets a delay in seconds at the output of the LVRT algorithm. When set to 60001 the time is infinite.	Yes
G4.3.3.2-Hysteresis Delay = 0.005 s	0.005 to 60.000 s	Sets a delay, in seconds, to the output of the LVRT algorithm if the hysteresis condition of parameter [G4.3.3.3-Hysteresis] is reached.	Yes
G4.3.3.3-Hysteresis = 2 %	1 to 15 %	Defines the hysteresis to obtain the output voltage value (voltage at which there is no dip). If the voltage is below the threshold, it will be considered as a voltage dip and will end when the voltage is "threshold" + "hysteresis".	Yes
G4.3.3.4-P Recover = 100.0 %	0.0 to 100.0 %	Sets the active power output of LVRT recovery. This is the P power value that the algorithm will apply on dip recovery before normal control starts acting again.	Yes
G4.3.3.5-Q Recover = 100.0 %	0.0 to 100.0 %	Sets the reactive power output of LVRT recovery. This is, the Q power value that the algorithm will apply on dip recovery before normal control starts acting again.	Yes
G4.3.3.6a-P Recover Time = Disabled	Disabled = 0.0; 0.1 to 60.0 s	Time during which, after an LVRT event, active power references remain frozen.	Yes
G4.3.3.6b-Q Recover Time = Disabled	Disabled = 0.0; 0.1 to 60.0 s	Time during which, after an LVRT event, reactive power references remain frozen.	Yes
G4.3.3.7-ID Recover Ramp = Disabled	Disabled = 19; 20 to 3000 %/s	Recovery ramp at the LVRT exit. If the parameter is configured as "Disabled" the ramp will be disabled. Otherwise, the set value will determine the slope (percentage per second) of P.	Yes
G4.3.3.8-IQ Recover Ramp = Disabled	Disabled = 19; 20 to 3000 %/s	Recovery ramp at the LVRT exit. If the parameter is configured as "Disabled" the ramp will be disabled. Otherwise, the set value will determine the slope (percentage per second) of Q.	Yes

### LVRT in PE UMD/PSCAD models - highlighted

Mode	Priority	Active Power	Reactive Power
0	-	Id = 0	Iq = k ⋅ dV
1	Р	Id = Id_prev	Iq = Iq_prev + k · dV
2	Q	Id = Id_prev	Iq = Iq_prev + k · dV
3	Р	Id = Id_prev	Iq = k ⋅ dV
4	Q	Id = Id_prev	Iq = k ⋅ dV
5	Р	P = P_prev	Iq = Iq_prev + k · dV
6	Q	P = P_prev	$Iq = Iq_prev + k \cdot dV$

Equival	ent LVRT	in inverter				
	G4.2.1.3	G4.2.1.4	G4.2.1.5	G4.2.1.6	G4.2.2.1	G4.2.2.2
Mode	Config	P mode	Q mode	PQ Prior	Id injection	lq injection
0	kdV	current	current	P/Q	-	-
1	Sprev + kdV	current	current	Р	-	-
2	Sprev + kdV	current	current	Q	-	-
3	Advance d	current	current	Р	X prev	kdV
4	Advance d	current	current	Q	X prev	kdV
5	Sprev + kdV	Power	current	Р	-	-
6	Sprev + kdV	Power	current	Q	-	-



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